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METHOD AND DEVICE FOR CONTROLLING  
AN INTERNAL COMBUSTION ENGINE

The present invention relates to a method and a device for controlling an internal combustion engine, particularly for controlling the injected fuel quantity. In the control of internal combustion engines, starting from operating parameters, a variable is specified that characterizes the fuel quantity. The variable characterizing the fuel quantity preferably  
5 concerns the fuel quantity, the duration of control for an actuator or another variable that characterizes the fuel quantity to be injected, such as the torque. Starting from this variable that characterizes the fuel quantity, control signals are specified for one or more actuators that influence the fuel metering.

As actuators, especially so-called pump-nozzle units are used, in which the pressure buildup  
10 and the control of the injected fuel quantity take place in a structural unit, or pump-line-nozzle systems are used. Correspondingly, as actuator, an injector may also be used to which the fuel is supplied under high pressure, and the injector merely controls the fuel metering.

Usually such actuators are encumbered with tolerances. This means that, for the same control signal, different injectors meter in different fuel quantities. Furthermore, tolerances are able  
15 to have the effect that, in response to the same operating conditions, for the same control signal, different fuel quantities are metered in.

#### Summary of the Invention

Because, starting from the rotary speed, from a variable characterizing the fuel quantity and from a variable characterizing the start of delivery, a correcting value for correcting the  
20 variable characterizing the fuel quantity is specified, tolerances, especially in the field of actuators, may be clearly reduced. This results in clearly more accurate fuel metering and thereby lower emissions.

#### Brief Description of the Drawing

In the following, the present invention is explained with the aid of the specific embodiment  
25 shown in the drawing. The only figure shows a block diagram of the device according to the present invention.

## Detailed Description of the Exemplary Embodiment

A quantity specification 100 specifies a quantity QK characterizing the fuel quantity to be injected. This usually reaches a control specification 110, which converts this signal into control signals for controlling an actuator 120. Corresponding methods and devices are known and are usually converted in engine control devices.

Output signal QK of the quantity specification, output signal N of a first sensor 130, output signal FB of a start of delivery control 135 make their way to an adjustment characteristics map 140, and output signal SW of a threshold value specification 150 reach a minimum selection 160. The output signal of minimum selection 160 reaches a maximum selection 170, at whose second input there is present the output signal of a sign change 180, that also has signal SW of threshold value specification 150 applied to it. A node 105 has applied to it output signal K of maximum selection 170, and at its second input the output signal of quantity specification 100 is present. Output signal QKK of node 105 is then applied to a control specification 110, which, in turn, correspondingly activates actuator 120.

As a rule, these elements are components of a control unit which activates the actuator. In internal combustion engines having several actuators, the elements should be designed in multiple fashion.

In adjustment characteristics map 140, as a function of various variables, correcting values K are stored, using which the fuel quantity QK to be injected is corrected. This correction is made in such a way that tolerances of the individual actuators are adjusted, that is, correcting values K are specified in such a way that all actuators measure in the same fuel quantity in response to the same signal of the quantity specification. Furthermore, correcting values K are specified in such a way that an actuator, at the same operating condition, especially at the same rotary speed, at the same start of delivery and at the same output signal QK of the quantity specification, meters in the same fuel quantity.

In this connection, it is particularly advantageous that, besides the fuel quantity and/or rotary speed N, in addition a signal that characterizes the start of delivery, is drawn upon to specify correcting value K. This is advantageous especially in systems in which the start of delivery influences the fuel quantity to be injected. This is so, in particular, in the case of so-called pump-nozzle systems and/or in the case of so-called pump-line-nozzle systems. As the signal that characterizes the start of delivery, preferably a signal is used that indicates the angular

position of the crankshaft or the camshaft, at which the injection begins. Alternatively, signals may also be used that indicate the beginning of the activation of the actuator.

Instead of the fuel quantity QK to be injected, alternatively a torque quantity, a signal that characterizes the duration of control, or another signal that characterizes the fuel quantity to be injected, may be used.

It is usually provided that an adjustment characteristics map 140 is assigned to each actuator, that is, to each pump-nozzle system. In this context, it is provided that the adjustment characteristics map is ascertained subsequently to the manufacture of the actuator. The data thus ascertained are then assigned to the actuator in a suitable manner, and, when the actuator is put into operation for the first time, the data are read into the control unit for the control of the internal combustion engine, and are stored in a suitable manner. During running operation, the correction according to the present invention then takes place based on these stored values.

In this context, various alternatives may be provided. On the one hand, the complete characteristics map may be ascertained, assigned to the actuator and then stored. On the other hand, it is possible to determine correcting values only at individual operating points, and to assign these to the actuator. During first operation, starting from these individual correcting values, the remaining characteristics map values may then be ascertained by using a suitable method. Alternatively, it may also be provided that the calculation takes place constantly. This procedure offers the advantage that only some few values have to be ascertained and assigned to the actuator.

The assignment of the data to the actuator may be developed in different ways. It may be provided, for instance, that the actuator and a data carrier, in which the data are inscribed, form a structural unit. On the other hand, it may be provided that the actuator and a data carrier, that includes an identification number, form a structural unit, and that then, in the light of this identification number, data are selected which, using another data carrier and/or a transmission means, are transmitted and then supplied to the control unit.

In one preferred specific embodiment, the output signals of the adjustment characteristics map are limited to maximum and minimum admissible values. For this, minimum selection 160 and maximum selection 170 are provided. Threshold value specification 150 specifies a threshold value which is directly supplied to the minimum selection and, with an inverted

sign, to maximum selection 170. The result is that the output signal of the adjustment characteristics map is limited to a maximum absolute value by minimum selection 160 and maximum selection 170. This is of advantage particularly if the values of the adjustment characteristics map is calculated starting from a few test points. In that case it may happen  
5 that, on account of calculating accuracies and other effects, very large or very small correcting values occur, that should not be taken into consideration.